

LECTURE 9

LINE INTEGRALS OF THE FIRST KIND

Line integral of the first kind

Definition 1. The set $\mathcal{C} \subset \mathbb{R}^n$ is called a **simple regular curve** in \mathbb{R}^n if there exists a 1-1 mapping

$$\mathbf{g}: (a, b) \rightarrow \mathcal{C}; \quad \mathbf{g}(t) = (g_1(t), \dots, g_n(t)), \quad (9.1)$$

that has a continuous derivative

$$\dot{\mathbf{g}}(t) = (g'_1(t), \dots, g'_n(t)) \neq (0, \dots, 0)$$

on the interval (a, b) .

It is therefore the set of points $\mathbf{x} = \mathbf{g}(t)$, i.e.,

$$(x_1, \dots, x_n) = (g_1(t), \dots, g_n(t)),$$

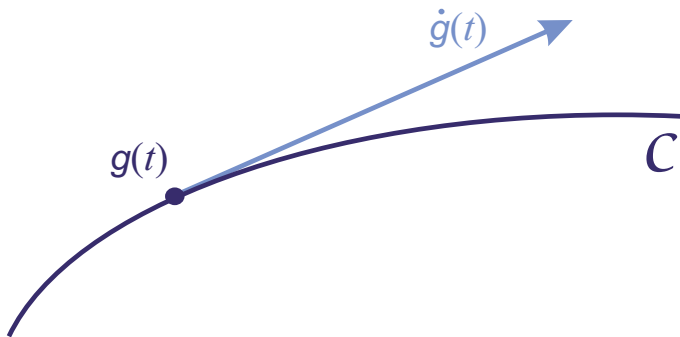
where the mapping \mathbf{g} satisfies the conditions stated above. This mapping is called a **parametrization of the curve \mathcal{C}** , the equation $\mathbf{x} = \mathbf{g}(t)$ is called a **parametric equation of the curve \mathcal{C}** .

The vector

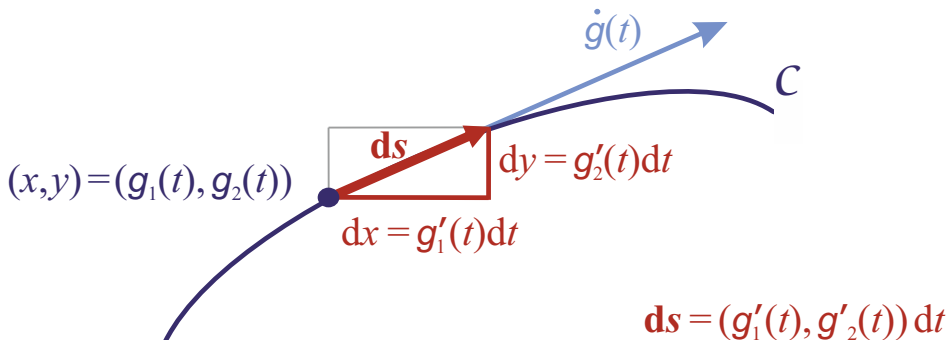
$$\dot{\mathbf{g}}(t) = (g'_1(t), \dots, g'_n(t))$$

is a **tangent vectorem to the curve \mathcal{C}** .

We can imagine a curve as a trajectory of a point that is moving in time. Then $\mathbf{g}(t)$ gives the coordinates of this point in time t , the vector $\dot{\mathbf{g}}(t)$ gives its instantaneous velocity.



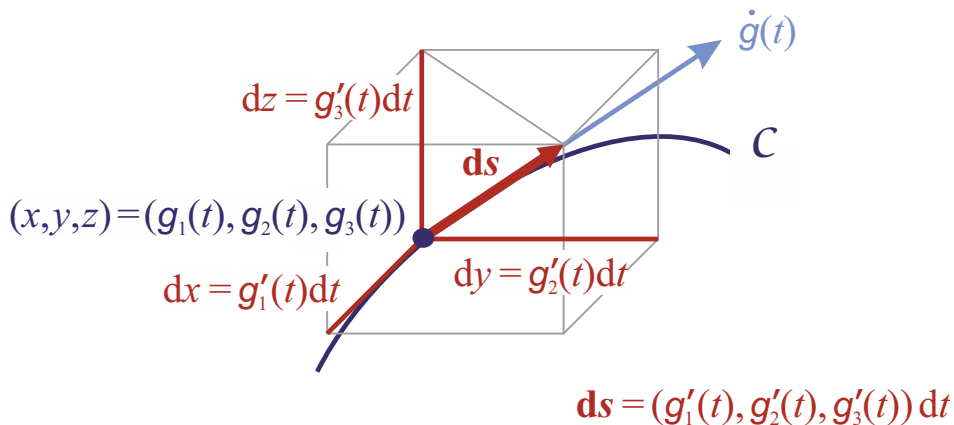
Special case: curves in \mathbb{R}^2



Length element ds of a simple regular curve \mathcal{C} with the parametrization $\mathbf{g}(t)$ is equal to

$$ds = \|\dot{\mathbf{g}}(t)\| dt = \sqrt{(g'_1(t))^2 + (g'_2(t))^2} dt \quad (9.2)$$

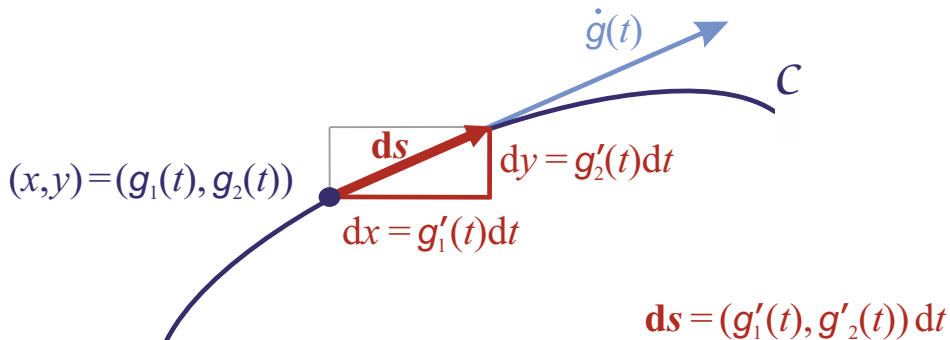
Special case: curves in \mathbb{R}^3



Length element ds of a simple regular curve C with the parametrization $\mathbf{g}(t)$ is equal to

$$ds = \|\dot{\mathbf{g}}(t)\| dt = \sqrt{(g'_1(t))^2 + (g'_2(t))^2 + (g'_3(t))^2} dt \quad (9.3)$$

Curves in \mathbb{R}^n



Length element ds of a simple regular curve C with the parametrization $\mathbf{g}(t)$ is equal to

$$ds = \|\dot{\mathbf{g}}(t)\| dt = \sqrt{(g'_1(t))^2 + \cdots + (g'_n(t))^2} dt \quad (9.4)$$

Line integral of the first kind

Definition 2. Let \mathcal{C} be a simple regular curve in \mathbb{R}^n , let $\mathbf{g}: (a, b) \rightarrow \mathbb{R}^n$ be its parametrization. Let $f: \mathcal{C} \rightarrow \mathbb{R}$ be a function. If the Riemann integral

$$\int_a^b f(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| dt \quad (9.5)$$

exists, then it is denoted by

$$\int_{\mathcal{C}} f ds \equiv \int_a^b f(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| dt \quad (9.6)$$

and called **the line integral of the first kind of the function f over the curve \mathcal{C} .**

Properties

Linearity

If α, β are real numbers and f, g functions, then the equality

$$\int_{\mathcal{C}} (\alpha f + \beta h) ds = \alpha \int_{\mathcal{C}} f ds + \beta \int_{\mathcal{C}} h ds \quad (9.7)$$

holds if the right side has a sense.

Additivity with respect to the curve

If $\mathcal{C} = \mathcal{C}_1 \cup \mathcal{C}_2$ and $\mathcal{C}_1 \cap \mathcal{C}_2$ contains at most the boundary points, then the equality

$$\int_{\mathcal{C}} f ds = \int_{\mathcal{C}_1 \cup \mathcal{C}_2} f ds = \int_{\mathcal{C}_1} f ds + \int_{\mathcal{C}_2} f ds \quad (9.8)$$

holds, if the right side has a sense.

☛ **Example.** Find the integral

$$\int_C x^2 ds, \quad \text{kde } C = \{(x, y) \in \mathbb{R}^2 \mid y = \ln x, x \in \langle 1, 2 \rangle\}.$$

Solution.

Consider the parametrization $x = g_1(t) = t, y = g_2(t) = \ln t$.

Then $\dot{\mathbf{g}}(t) = (1, \frac{1}{t}) \neq \mathbf{o}$.

$$\int_C x^2 ds = \int_1^2 t^2 \left\| \left(1, \frac{1}{t} \right) \right\| dt = \int_1^2 t^2 \sqrt{1 + \frac{1}{t^2}} dt = \int_1^2 t \sqrt{t^2 + 1} dt =$$

$$= \left| \begin{array}{l} t^2 + 1 = u, \quad 2t dt = du \\ t = 1 \Rightarrow u = 2 \\ t = 2 \Rightarrow u = 5 \end{array} \right| =$$

$$= \frac{1}{2} \int_2^5 u^{1/2} du = \frac{1}{2} \cdot \frac{2}{3} [u^{3/2}]_2^5 = \frac{1}{3} (5^{3/2} - 2^{3/2}).$$

☛ **Example.** Find the integral

$$\int_{\mathcal{C}} (x + y) ds,$$

where \mathcal{C} is a line segment with the boundary points $A = (0, 0)$, $B = (1, 2)$.

Solution.

Parametrization: $x = t$, $y = 2t$, $t \in \langle 0, 1 \rangle$. For this parametrization we obtain tangent vector $\dot{\mathbf{g}}(t) = (1, 2)$ with $\|\dot{\mathbf{g}}(t)\| = \sqrt{5}$. Thus

$$\int_{\mathcal{C}} (x + y) ds = \int_0^1 (t + 2t) \sqrt{5} dt = \frac{3}{2} \sqrt{5}.$$

• **Example.** Find the integral

$$\int_{\mathcal{C}} \frac{z^2}{x^2 + y^2} ds,$$

where \mathcal{C} is one thread of the screw $x = r \cos t$, $y = r \sin t$, $z = rt$, $t \in \langle 0, 2\pi \rangle$.

Solution. Tangent vector:

$$\dot{\mathbf{g}}(t) = (-r \sin t, r \cos t, r)$$

is size: $\|\dot{\mathbf{g}}(t)\| = r\sqrt{2}$. Then

$$\int_{\mathcal{C}} \frac{z^2}{x^2 + y^2} ds = \int_0^{2\pi} \frac{r^2 t^2}{r^2} r\sqrt{2} dt = \frac{8r\pi^3\sqrt{2}}{3}.$$

Some applications

Length $s(\mathcal{C})$ of a curve \mathcal{C} :

$$s(\mathcal{C}) = \int_{\mathcal{C}} ds = \int_{t_0}^{t_1} \|\dot{\mathbf{g}}(t)\| dt$$

Weight $m(\mathcal{C})$ of a curve \mathcal{C} with the length density σ :

$$m(\mathcal{C}) = \int_{\mathcal{C}} \sigma ds = \int_{t_0}^{t_1} \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| dt$$

Static moments in \mathbb{R}^2 :

$$S_y(\mathcal{C}) = \int_{\mathcal{C}} x\sigma \, ds = \int_{t_0}^{t_1} g_2(t)\sigma(\mathbf{g}(t))\|\dot{\mathbf{g}}(t)\| \, dt$$

$$S_x(\mathcal{C}) = \int_{\mathcal{C}} y\sigma \, ds = \int_{t_0}^{t_1} g_1(t)\sigma(\mathbf{g}(t))\|\dot{\mathbf{g}}(t)\| \, dt$$

Coordinates $x_{cg}(\mathcal{C})$, $y_{cg}(\mathcal{C})$ of a centre of gravity of a curve \mathcal{C} :

$$x_{cg}(\mathcal{C}) = \frac{S_y(\mathcal{C})}{m(\mathcal{C})} = \frac{\int_{\mathcal{C}} x\sigma \, ds}{m(\mathcal{C})},$$

$$y_{cg}(\mathcal{C}) = \frac{S_x(\mathcal{C})}{m(\mathcal{C})} = \frac{\int_{\mathcal{C}} y\sigma \, ds}{m(\mathcal{C})}$$

Static moments in \mathbb{R}^3 :

$$S_{yz}(\mathcal{C}) = \int_{\mathcal{C}} x \sigma \, ds = \int_{t_0}^{t_1} g_1(t) \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| \, dt$$
$$S_{xz}(\mathcal{C}) = \int_{\mathcal{C}} y \sigma \, ds = \int_{t_0}^{t_1} g_2(t) \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| \, dt$$
$$S_{xy}(\mathcal{C}) = \int_{\mathcal{C}} z \sigma \, ds = \int_{t_0}^{t_1} g_3(t) \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| \, dt$$

Coordinates $x_{cg}(\mathcal{C})$, $y_{cg}(\mathcal{C})$, $z_{cg}(\mathcal{C})$ of the centre of gravity of \mathcal{C} :

$$x_{cg}(\mathcal{C}) = \frac{\int_{\mathcal{C}} x \sigma \, ds}{m(\mathcal{C})}, \quad y_{cg}(\mathcal{C}) = \frac{\int_{\mathcal{C}} y \sigma \, ds}{m(\mathcal{C})}, \quad z_{cg}(\mathcal{C}) = \frac{\int_{\mathcal{C}} z \sigma \, ds}{m(\mathcal{C})}.$$

Moments of inertia in \mathbb{R}^2 :

$$I_x(\mathcal{C}) = \int_{\mathcal{C}} y^2 \sigma \, ds = \int_{t_0}^{t_1} g_2^2(t) \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| \, dt$$

$$I_y(\mathcal{C}) = \int_{\mathcal{C}} x^2 \sigma \, ds = \int_{t_0}^{t_1} g_1^2(t) \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| \, dt$$

Moments of inertia in \mathbb{R}^3 :

$$I_x(\mathcal{C}) = \int_{\mathcal{C}} (y^2 + z^2) \sigma \, ds = \int_{t_0}^{t_1} (g_2^2(t) + g_3^2(t)) \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| \, dt$$

$$I_y(\mathcal{C}) = \int_{\mathcal{C}} (x^2 + z^2) \sigma \, ds = \int_{t_0}^{t_1} (g_1^2(t) + g_3^2(t)) \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| \, dt$$

$$I_z(\mathcal{C}) = \int_{\mathcal{C}} (x^2 + y^2) \sigma \, ds = \int_{t_0}^{t_1} (g_1^2(t) + g_2^2(t)) \sigma(\mathbf{g}(t)) \|\dot{\mathbf{g}}(t)\| \, dt$$